

Why is High Resolution AeroMagnetic (HRAM) data better for exploration purposes than the magnetic data available from the GSC?



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Fig. 3.5

Fig. 3.6

Fig. 3.7

hat is the difference between these two sources of data when it mes to solving exploration problems? The difference is solving. The God data, in gridded form, does not have adequate quency content to solve structural problems, except on a very

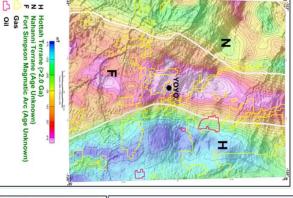


Fig. 2. HRAM total magnetic field draped on shaded topography showing structural terrane boundary and oil and gas prospects.

This poster compares in detail the HRAM data with the GSC gridded aeromagnetic data, using data from North Eastern British Columbia (NEBC) (Figures 1 and 2).

The GSC data is a synthesis of many virtages of aeromagnetic surveys which have been mergade together at the grid weet, in general, these surveys are fellow at relatively high althodes (e.g., 300 m bancmetric above the highest loopergaphy in the seasy) without GST navigation with relatively wide line spacings (typically 1 x 3 miles). The mergad data have been gridded using a 2 km croil size.

a review GSC surveys, flown since 1992, have used GPS navigation. Julgiare line specings, and often they have been from all lower validors. For the most part these news surveys are in southern ents, southwest Sessiathewan, and in the Mackenzie Valley and botherse Delta. The comparisors in this poster are not vall of or fless were surveys, which are, in fact, HPAM surveys flown by the GSC, favorable in fire format at very low costs.

isser results indicate that the GSC data is good enough to map deep, increal geological structures (e.g., pediological strumes), but they are pood enough to map stellow subtle features in the sedimentary pood enough to map stellow subtle features in the sedimentary in in in contrast, the HRAM data has the frequency content to make the pediological features in the sedimentary basis, as well the in the

NEBC Comparisons

Fire radial power spectra of the two data sets demonstrate that the GSC tata is unable to resolve geological features located at shallow depths i.e., depth < 3.0 km) whereas the HRAM data is able to resolve peological features located as shallow as 400 m (Figures 5.1 and 5.2).

iltering is a way of separating signals of different inhance anomalous features with a certain wavelength.

This comparison demonstrates that the HRAM data has better resolution than the GSC data because of its higher frequency content. The high-frequency signal carries information related to subtle and table destines in the infra-sedimentary rocks such as faults, paleochannels and kimberlifes.

Magnetic lineaments in the intra-sedimentary rocks aments are associated with shear zones, faults and subcr

Remagnetized faults and fractures ocarbon brines as well as hydrothermal

ordet to illustrate this point further we have decomposed the total agretic field grids into four bandpass filters of verying wavelengths indexing different peological depths. These are: 1.2 - 4.8 km (shallow ppl.), 30 - 6.0 km (motion depth), 4.8 - 9.6 km (deep) and 8.0 - 2.4 (rowy deep), within this crust) (Figures 3.3 - 37 and 4.4 - 4.7). For a by crude translation from wavelength to depth, divide wavelength by 9. Sa a bandpass of 3.0 - 6.0 km (wavelength has most resolution in 9 sample of 1.5 - 3.0 km dopsh, but signal from other depths will also so sample of 1.5 - 3.0 km dopsh, but signal from other depths will also

